

Abstract

A control lever for a manipulator, used in particular for heavy construction machines, comprising a frame defining a cavity, and at least one control button which is actuated by an operator in order to control hydraulic jacks, characterized in that at least one control button comprises at least one lower insulating layer and one upper insulating layer placed on top of each other, whereby a lower conducting layer is fixed to the lower layer, and a second upper conducting layer is arranged opposite the first where the control button is arranged, both elements being separated in the absence of pressure exerted by the finger of the operator and being able to enter into contact when the pressure exerted when the pressure exerted by the finger of the operator is transmitted to the upper layer, whereupon said upper layer becomes deformed and transmits said movement to the upper conducting element, whereupon the contact between the lower conducting elements and upper conducting elements closes an electric circuit generating an electronic control signal.